Build Instructions

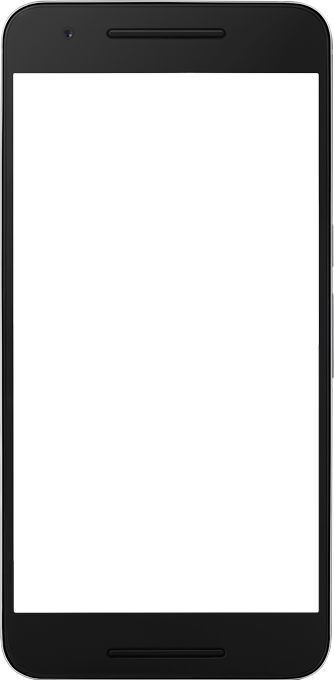
Parts Crib Database

By: Masoud Rahguzar

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System Diagram

The purpose of the humber parts crib database project is to be able to scan barcodes on student id cards and the associated part and then placed in a database. Now understanding what the humber part crib database project, the system diagram can be easily interpreted.







Process

Output

Input

Bill of Materials/Budget

The main materials required for my project are a raspberry pi, webcam and barcodes. Added features/materials PCB for light indicator, sound bar and acrylic box. The PCB and acrylic box were provided by the school. Also, the raspberry pi required a monitor, keyboard and mouse to setup remote desktop or another functionality. My excel version of my budget is also provided in my GitHub page.



Time Commitment

The time commitment for my project took about 15 weeks to complete in its entirety. Firstly, it began with ordering the parts and delivery which took week and a half (week 2 & 3) to come in. Once everything arrived, I then setup my raspberry pi and all of its components which took my about 1 hour to setup. Then thru week 5 I printed out my PCB and started soldering everything. The soldering approximately took me about 2 hours to complete at school. Afterward, at week 6 and week 7 I started to test my raspberry pi and its components which took me about 6 hours in its entirety. Firstly, I tested if the PCB by implementing the code given by the teacher that can test if the lights work. Then I started implementing the code in which will scan barcodes with my webcam. Next, during week 9 I created I remote desktop with my raspberry pi and laptop so I could connect it remotely without using an external monitor, keyboard and mouse. Lastly, during week 12 and 13 I began and created my acrylic box, the box design took me about 1 hour to complete and the lazar cut took about 20 minutes. Here at the bottom is all the task I completed and its easier to understand.

Time Commitment:

Ordering Parts and Delivery 🡪 2 weeks

Raspberry Pi Setup 🡪 1 hour

PCB Soldering 🡪 2 hours

Testing PCB 🡪 1 hour

Coding 🡪 5 hours

Remote Desktop 🡪 1 hour

Mechanical Assembly 🡪 15 minutes

Acrylic box assembly 🡪 10 minutes

All these up top tasks are completed in order.

Mechanical Assembly

The assembly of my project is very simple first connect the PCB on top of the raspberry pi which contains the light indicator. Secondly, proceed and connect the webcam to the USB port on the raspberry pi and then lastly connect the raspberry pi to a power outlet.

PCB / Soldering

Humber college provided my PCB which is called the Modular Sensor Hat. The PCB contains 20 pin, two 4 pin, 5 pin, a couple of resistors, transistors and a light. Before soldering I took care of my safety by wearing my safety glasses and making sure my work place was clear. The soldering was fairly simple to complete because of the schematic given by the school.

Power Up

The power begins with the setup of the raspberry pi. First connect to the raspberry pi to a monitor, keyboard and mouse and then to a power outlet. Once powered on the setup of the OS will commence which will take a few minutes. When complete open up the terminal and start updating the raspberry pi “sudo apt-get update” which will update it the latest version. Afterwards, PCB must be tested because it will be used in my project as a light indicator. The code for the light on the PCB was given by Humber College and could be run by running this command in the terminal “sudo ./traffic2B” which will make the light change red to green every few seconds. The code is also in my GitHub page.

Unit Testing

The uniting testing begins the PCB as mentioned in the power up. It is recommended to use the code that is given by Humber College or at my GitHub page to test if the light indicator works. The light indictor can work the command “sudo./traffic2B” is used. The next step is to check if the webcam work. This can be done by installing FSWEBCAM by putting “sudo apt-get install fswebcam” in the command line of the terminal which will install an easy way to check if the camera works. Once installed type “fswebcam image.jpg” in the command line and if it takes a picture with good quality the webcam works. After this, the code created for this project can be used which is in my GitHub page. The program can run by typing “python barcode.py” in the command line.

My project can be reproducible by following by instruction because there is not a lot of steps to get it working.